

# Road to Cloud Ecosystem

## CAEdge, Virtualization, HPC, Zones

# Agenda

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1	From SW-Defined Vehicle to User-Defined Vehicle	Gilles Mabire	3
2	CAEdge: SDV Development with a Cloud-Based Framework	Andreas Greff	10
3	Virtualization	Andreas Greff, Karsten Michels	18
4	Server-Zone Portfolio	Karsten Michels, Gerhard Guentner	27
5	Function as a Product	Gerhard Guentner	46
6	Summary	Gilles Mabire	52

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# Transformation of Mobility

## Global trends revolutionizing the automotive industry



Automated Driving



Cloud Services



Internet of Things



UX Applications



Shared Mobility



36 %

Cars with over-the-air capabilities by 2026



2026

66% of OEMs plan to partner with software firms and system integrator firms



+400 %

New vehicles based on common software platforms grow from 7% today to 35% by 2031



\$640 billion

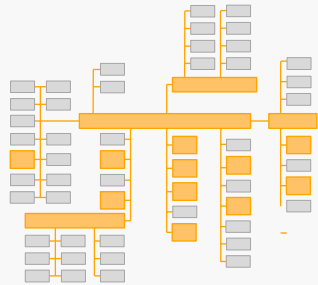
By 2031 software-based features and services will be a market worth \$640 billion

# Vehicle Architecture Transformation

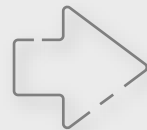
## A radical shift in the automotive industry

Up2now **Going forward**

PAST

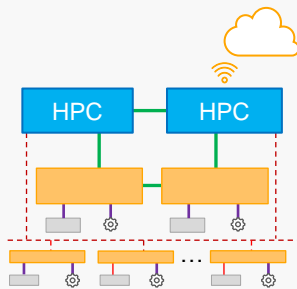


Distributed Architecture



REVOLUTION

TODAY

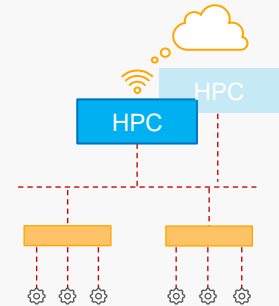


Server-Zone Architecture with domain / x-domain HPCs



EVOLUTION

FUTURE

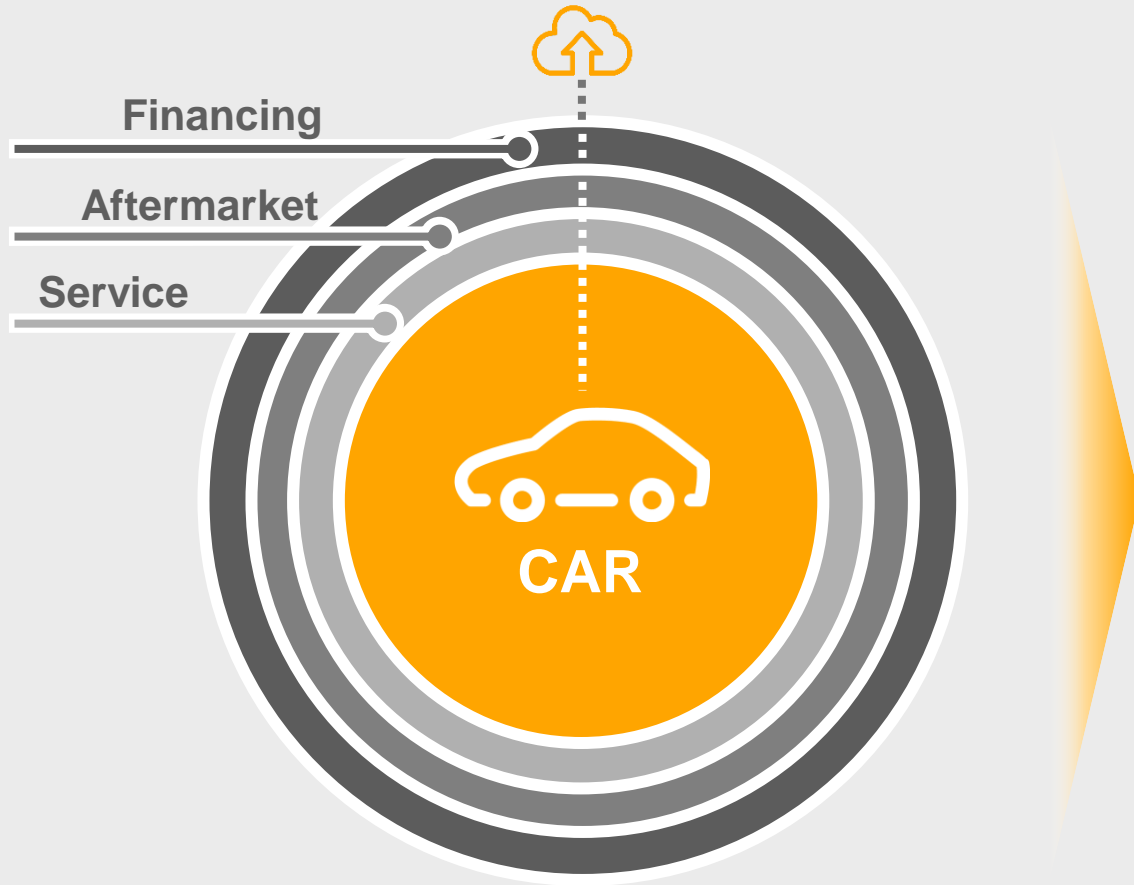


Server-Zone Architecture with Central HPC

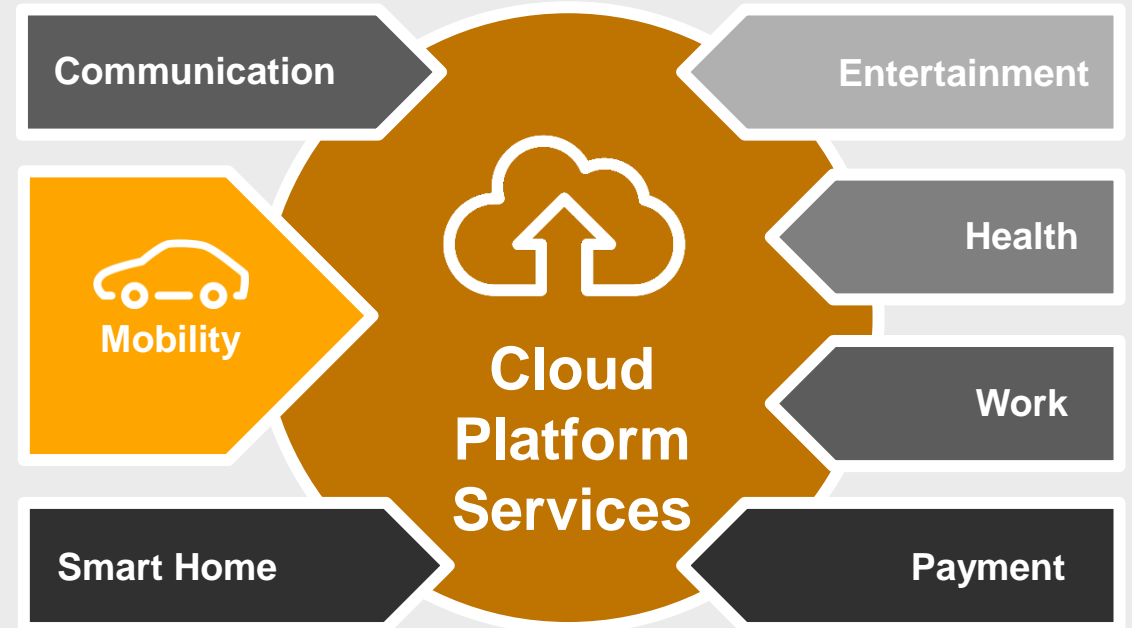
HPC: High-Performance Computer

# Transformation of Mobility

The car is turning into a system within a system of systems

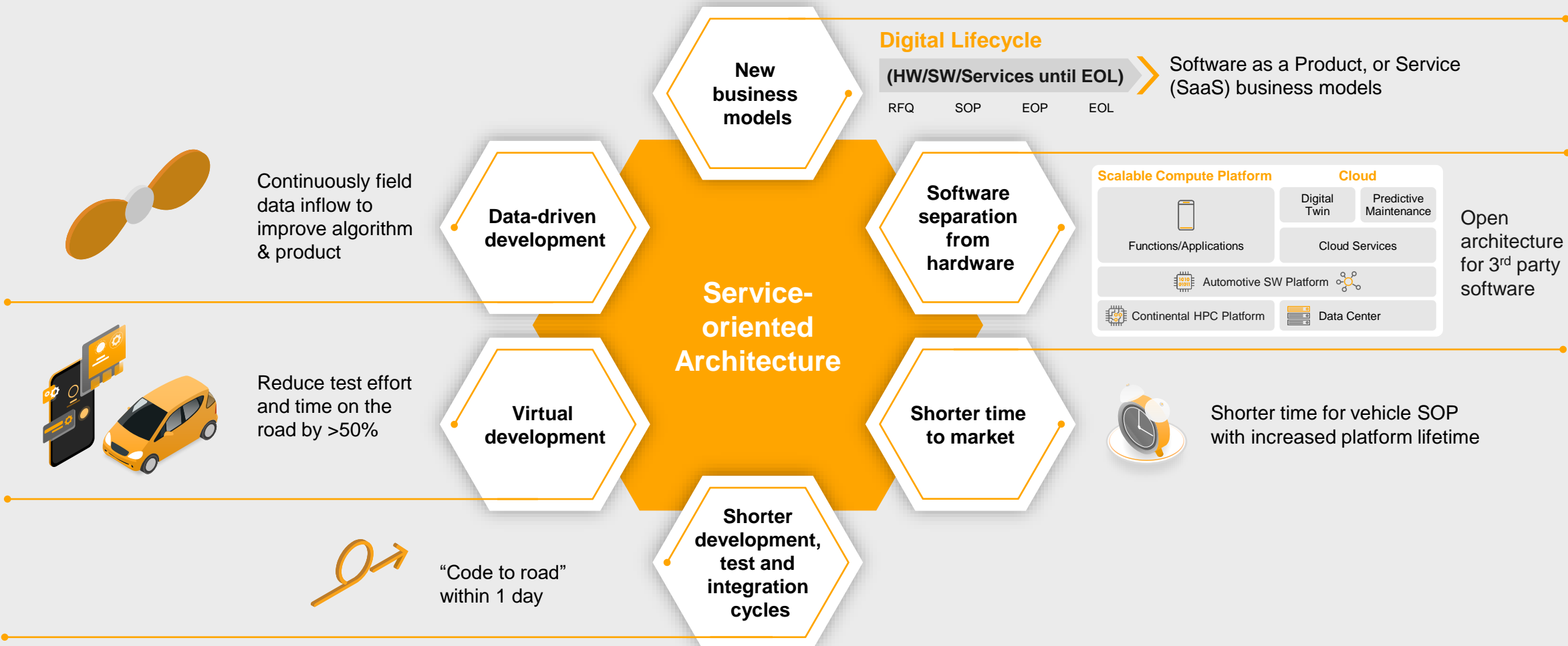


## Internet Connectivity



# Advantages of the Software-defined Vehicle

## Service-oriented Architecture as Transformation Enabler



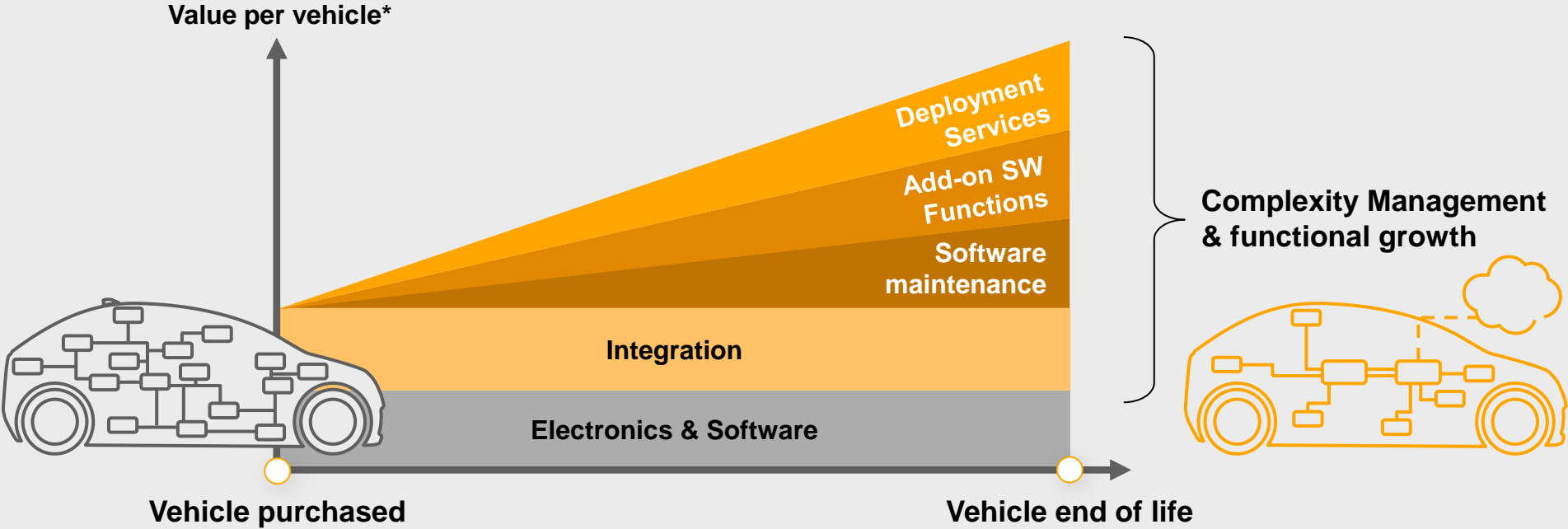
HW: Hardware; SW: Software; HPC: High-Performance Computer; RFQ: Request for Quote; SOP: Start of Production; EOP: End of Production; EOL: End of Life

# Software-Defined Vehicle (SDV)

## extends business lifecycle

Up2now

Going forward



\* Not to scale; for illustrative purposes only

# Road to Cloud Ecosystem

## Enable. Develop. Integrate.

**In the Software-defined Vehicle (SDV), functions are enabled by software.**

Decoupling software from hardware enables swift and continuous development, testing & implementation of new functions and software updates throughout vehicle lifetime.

**OUR APPROACH:**  
**The road to cloud ecosystem**

**Within this we deliver:**

- › enabling technologies,
- › hardware components and
- › software solutions and functions.



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**CAEdge**

**Continental  
Automotive Edge  
Framework**

**The Comprehensive  
Framework for Automotive  
Software Development**



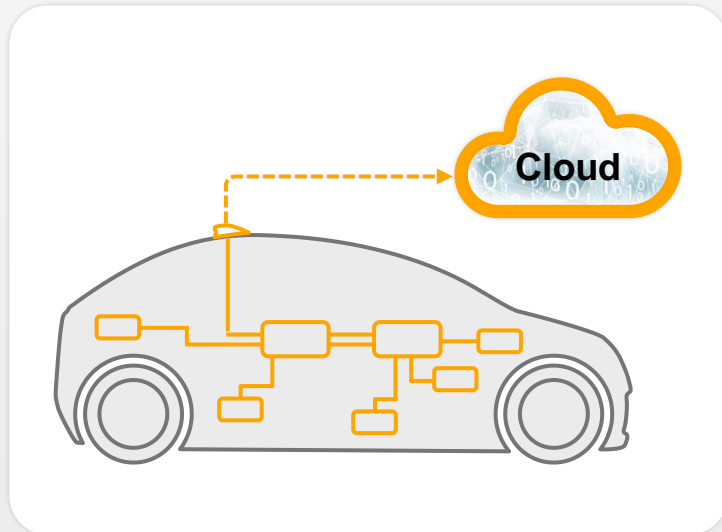
CAEdge is the ecosystem to embrace software-defined vehicles, from architecture to software integration.

With the most diverse building blocks, it is the tool set for individual development, optimal collaboration, testing and validation.

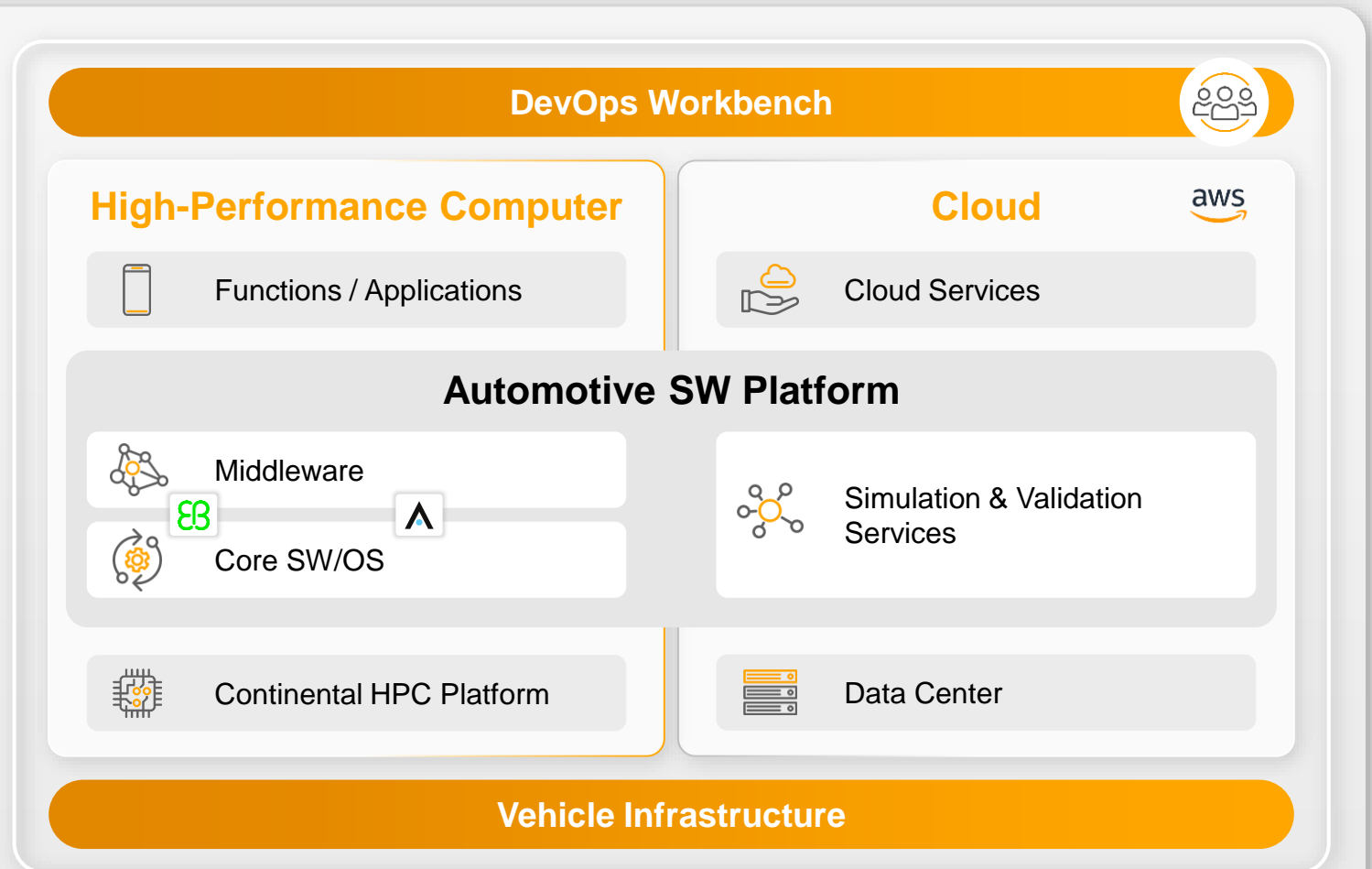
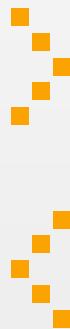


# Our Approach: Continental Automotive Edge Framework

## Our Full-Stack IoT Architecture Solution



Software-defined vehicle



\*  $\mu$ P: Micro-Processor, SoC: System on Chip, SoM: System on Module; CI/CD: Continuous Integration / Continuous Deployment

# CAEdge

is a cloud-based framework for:

SW development decoupled from HW development

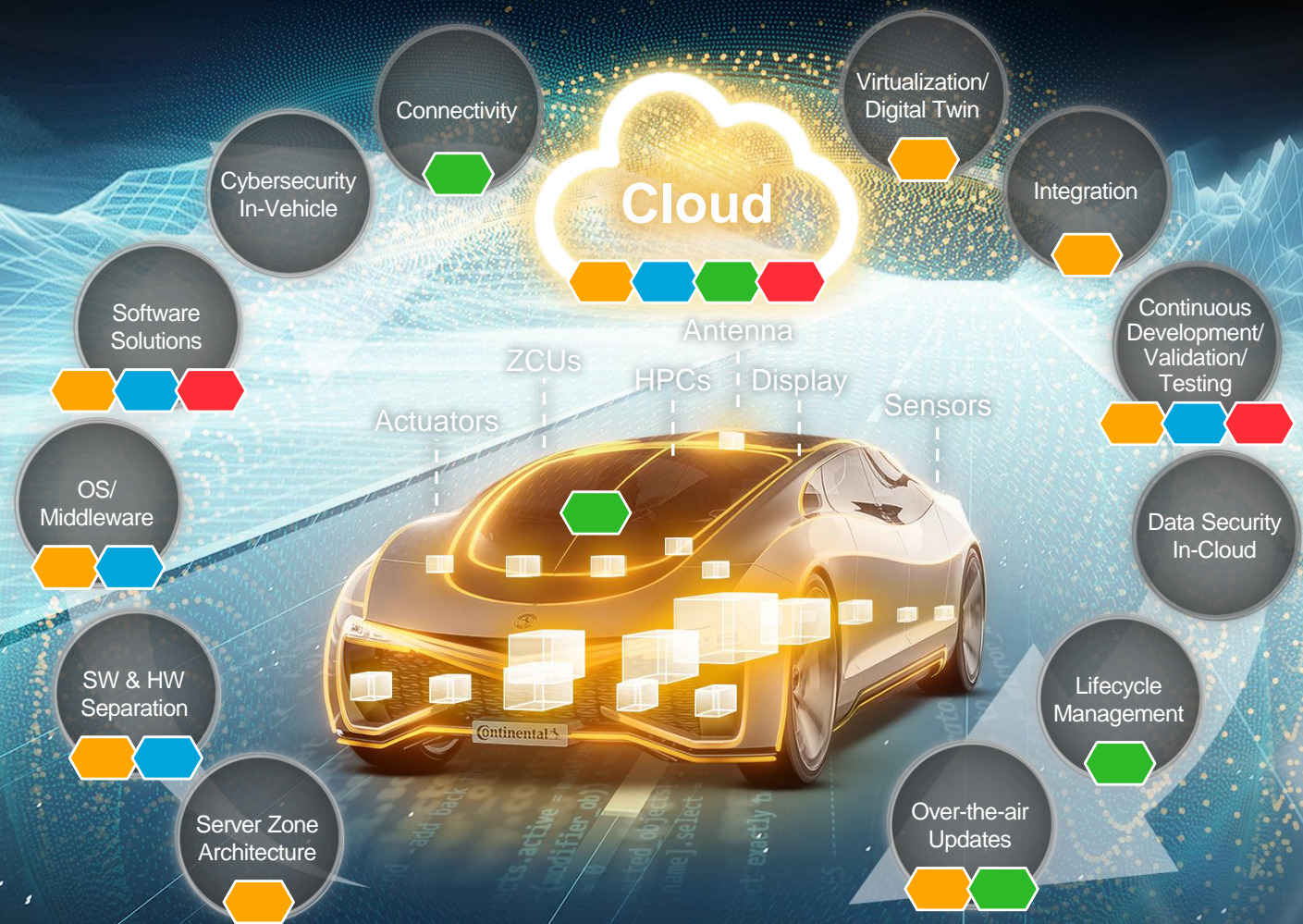
Virtualization and simulation

Seamless collaboration

Validation and improvement of system functions

# Continental Automotive Edge Framework

## Key for SDV Development and Deployment



With CAEdge you can:

### Evaluate

your SW-architecture before you build physical devices

### Run

a new function within 1 day in any physical car at anytime

### Share

the same target hardware for all developers worldwide instantly

### Drive

1 million km in simulation at your desk in 1 day

# CAEdge Offerings for the Software-defined Vehicle



**Evaluate**

› vECU Creator



**Run**

- › Cloud-based Workbench for Software Development
- › Continental Cooperation Portal



**Share**

- › Hardware Development Kit HDK 2.0/3.0
- › Hardware Farm



**Drive**

- › Workbench for Data-driven Development

# Continental Automotive Edge Framework

Automotive System Development from Idea to Roll out in Just a Glimpse

**CAEdge enables faster development and deployment**

**CAEdge provides interchangeable building blocks**

**Customers can start immediately**

**Modular and scalable compute platform**

**Automotive grade designed building blocks**

**Cohesive, integrated tool framework**

**Non-differentiating automotive-grade OS and middleware**

**Cloud as scalable extension of embedded and on-prem resources**

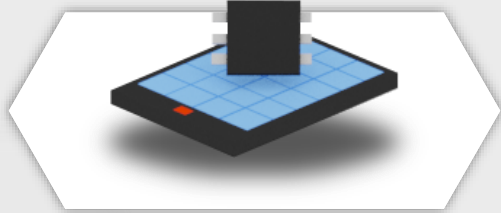
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# Automotive Virtualization Levels



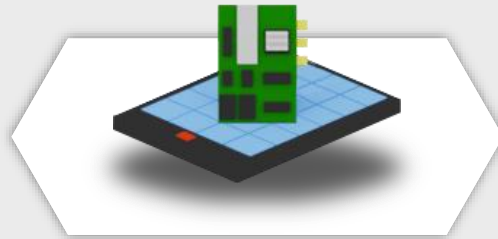
## Virtual Micro

Hardware is simulated to run the real target binary software on a PC

### Target to test:

- › MCAL/BSW functions

SYNOPSIS® Virtualizer



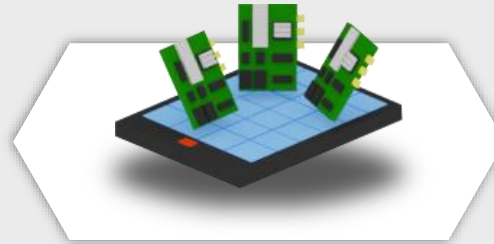
## Virtual ECU

Lower software layers are simulated to run target C code on a PC

### Target to test:

- › BSW functions
- › ECU communication
- › ASW functions
- › SW modules

SYNOPSIS® Silver



## Virtual ECU-System

Several ECUs are simulated to run ASW functions and their interactions

### Targets to test:

- › ASW functions
- › SW modules
- › ECU communication
- › Network/cloud services

CAEdge



## Virtual Car

All relevant ECUs are simulated to run all system and ASW functions as well as their interactions

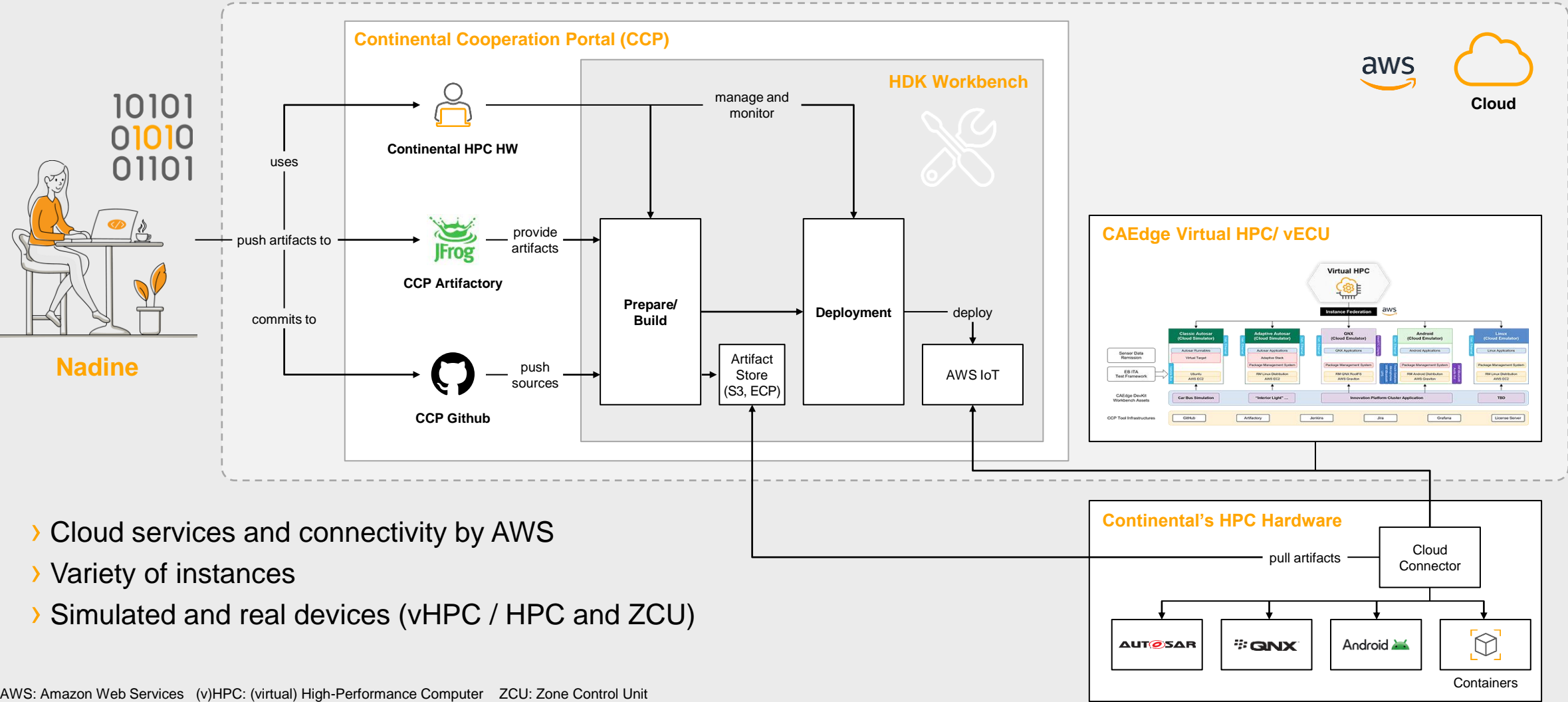
### Targets to test:

- › System functions
- › ASW functions
- › SW modules
- › Communication
- › Network/cloud services

In the future

# HPC Development Kit / Virtual HPC Workbench

## Development Workflow



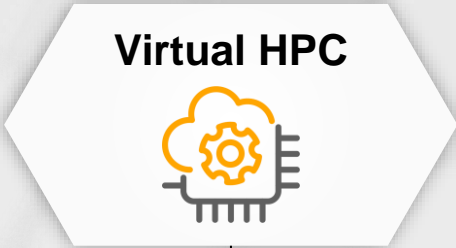
- > Cloud services and connectivity by AWS
- > Variety of instances
- > Simulated and real devices (vHPC / HPC and ZCU)

AWS: Amazon Web Services (v)HPC: (virtual) High-Performance Computer ZCU: Zone Control Unit

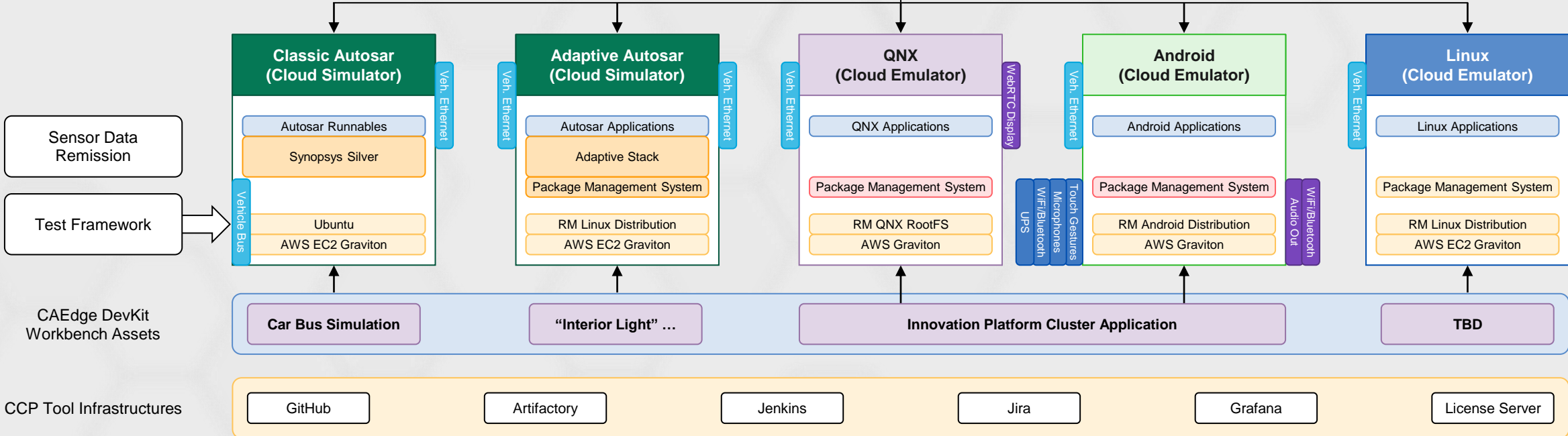
# CAEdge Virtual HPC / vECU

## Digital Twin of the Physical HPC

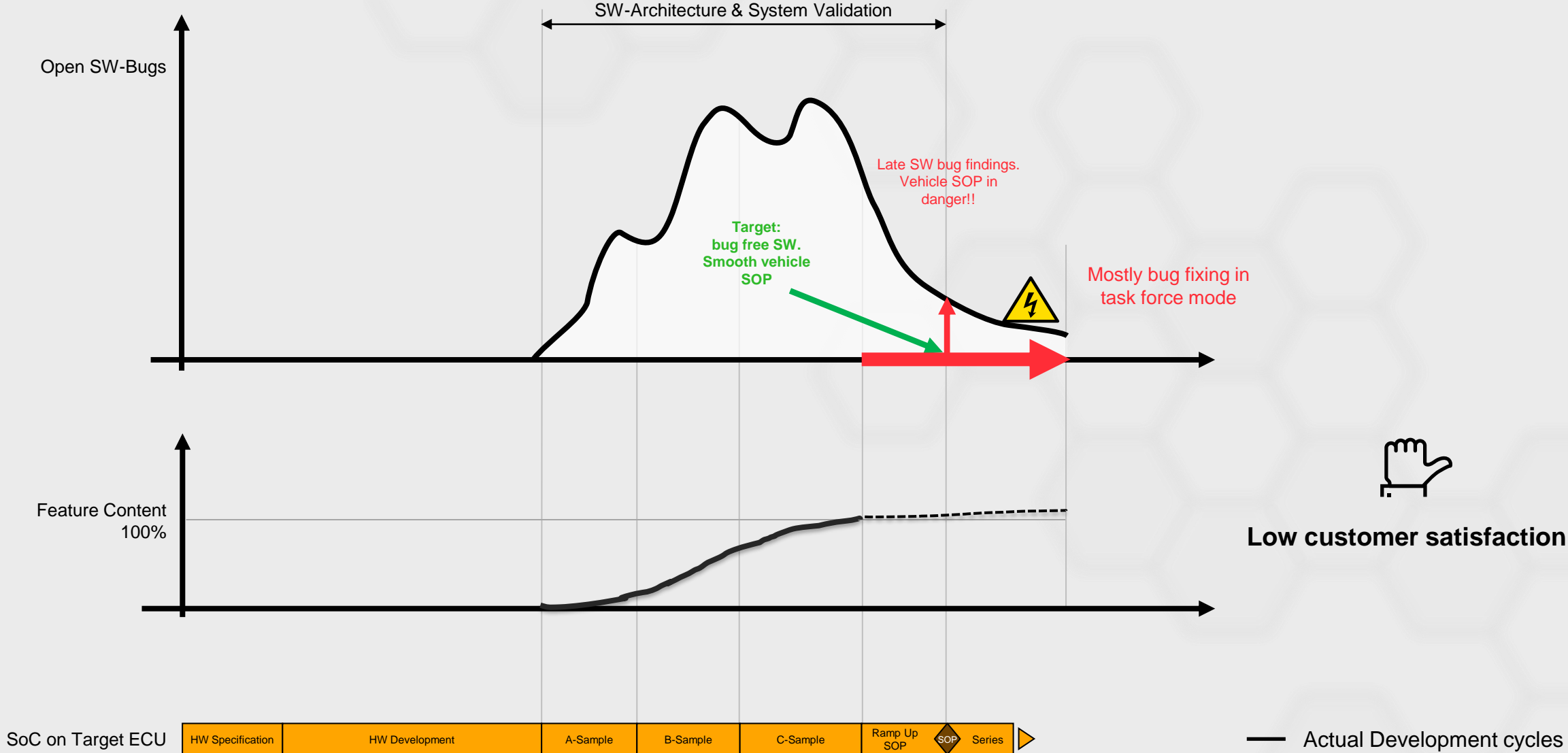
5 instances available  
in the vECU Creator



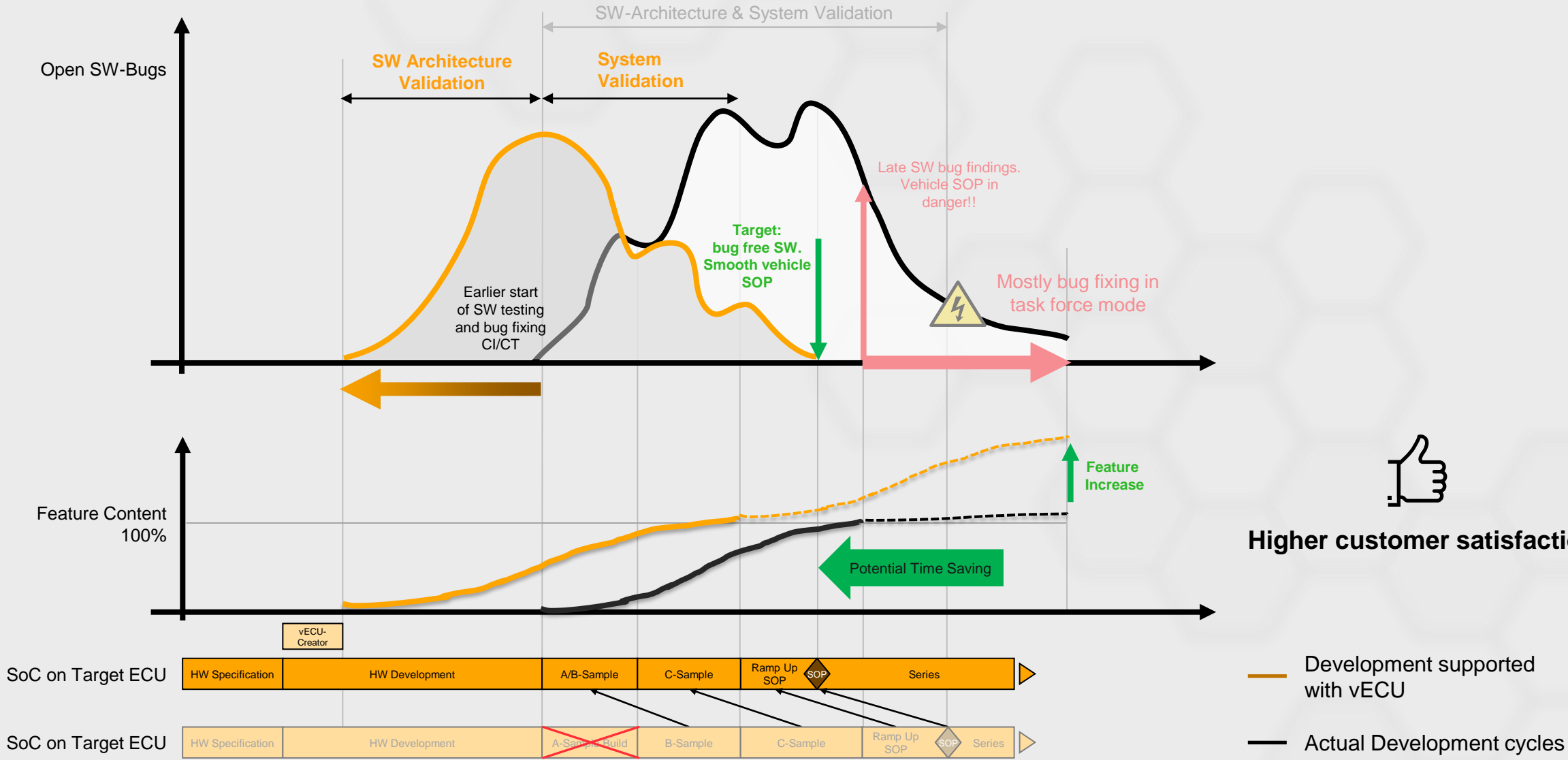
Instance Federation



# Situation Today Without HW/SW Virtualization



# Situation Today With HW/SW Virtualization

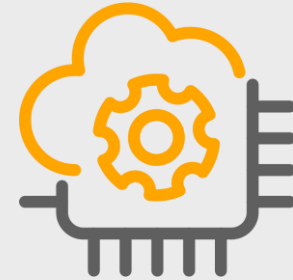


# Virtualization / vECU Creator

## Advantages

### Targets/Achievements

- › **Risk reduction** by separation/decoupling from SW-architecture validation and system validation
- › **Resource-saving** development
- › **Save costs** for samples
- › Save costs for HiL tests through the use of in **parallel virtual tests**



### Result

- **Smooth entry into series production**
- **Reduction of task forces**
- **Faster SOP**
- **Faster transition to update/upgrade development mode**
- **Higher customer satisfaction**

# Virtualization Examples

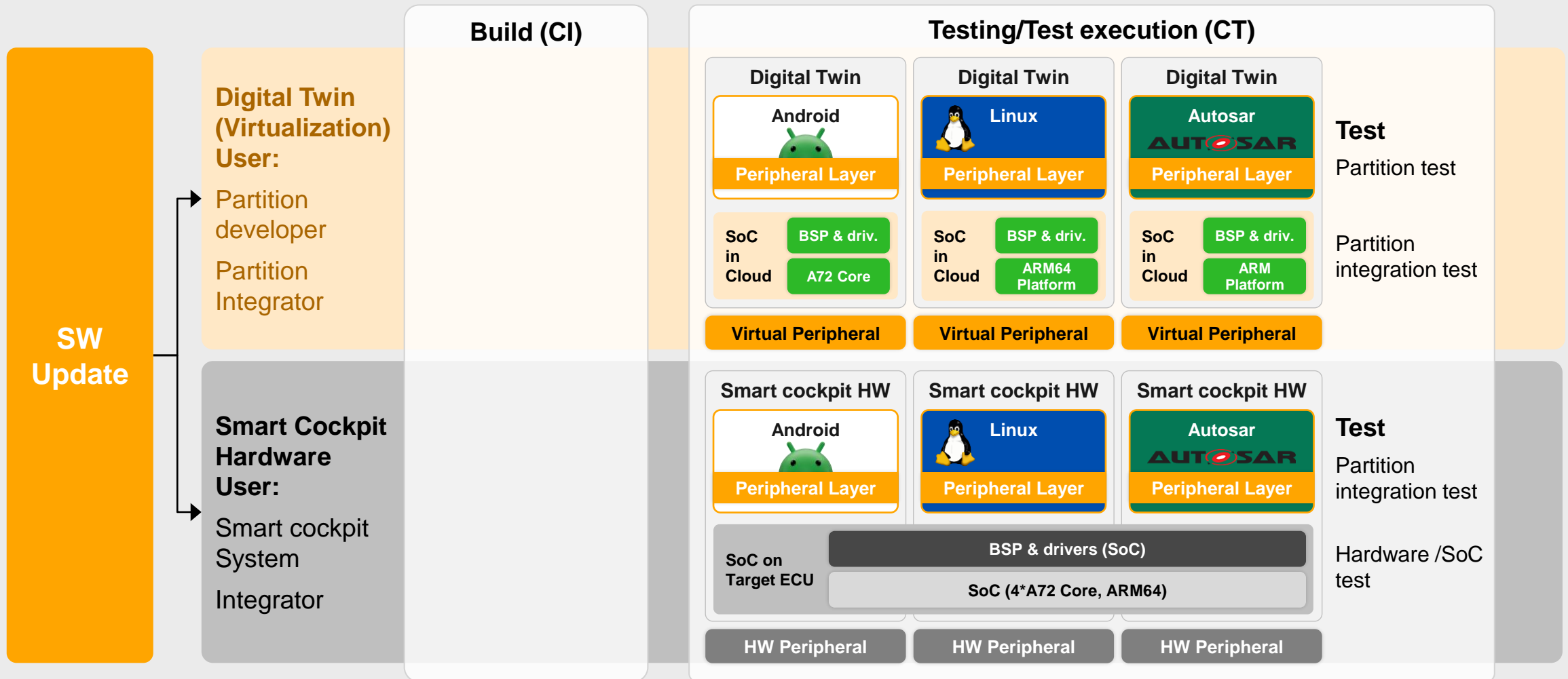
## Demonstration Projects



Example: Virtualization of Smart Cockpit HPC

# Smart Cockpit HPC Virtualization

## Integration and Test Strategy for Multiple Partitions – Testing



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# Full Scale Solution Provider for the SDV

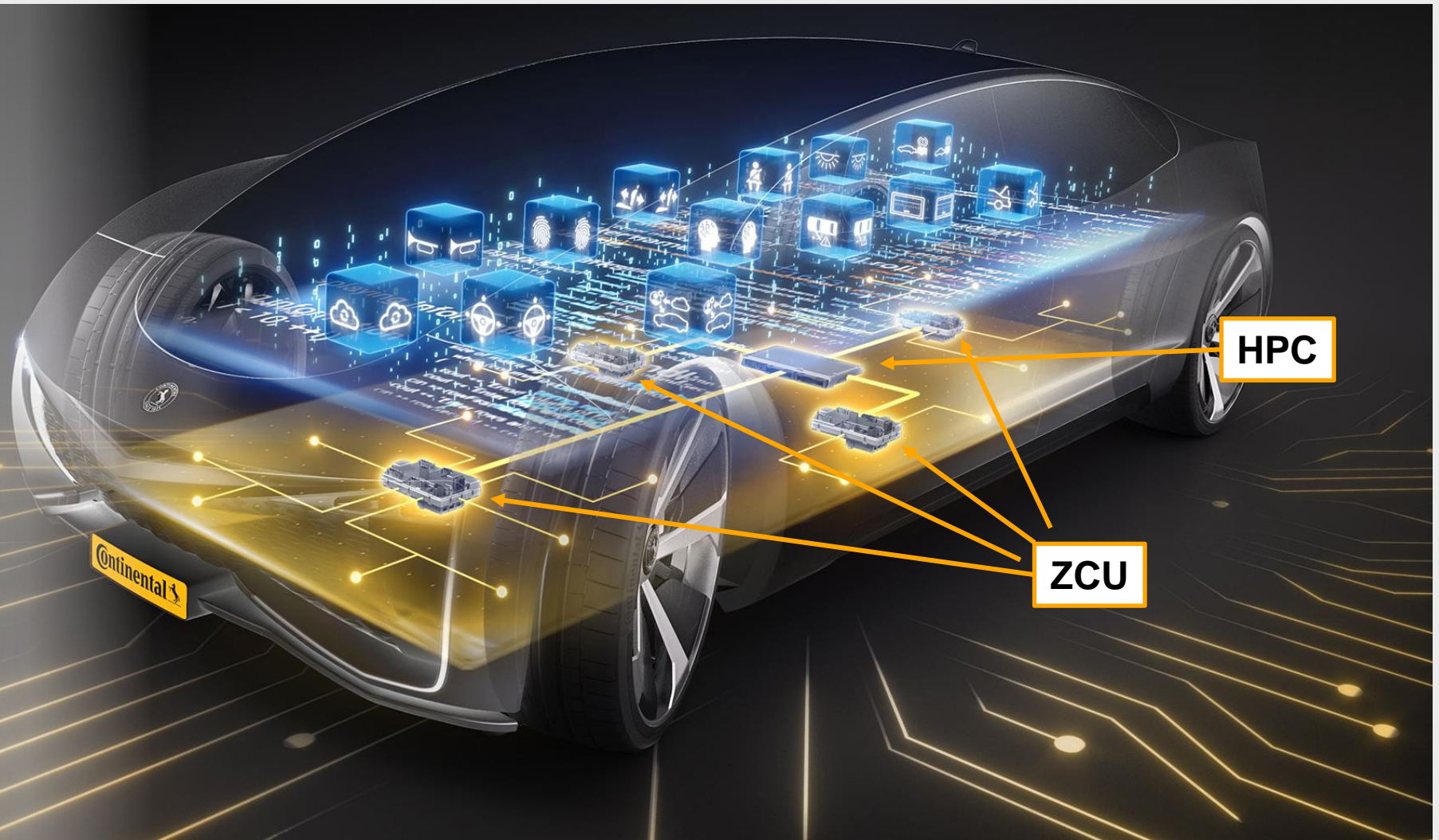
## Function Application Layer / HW Backbone Provider

### Function Application Layer

- > Function as a Product (FaaS)
- > Services

### Hardware Backbones

- > High-Performance Computer (HPC)
- > Zone Control Unit (ZCU)



# HPC Product Portfolio

## Flexible Solutions for Unique Customer Demands

Vehicle  
Control HPC



Cockpit HPC  
(Cluster + Infotainment)



Software  
Development &  
Integration,  
Virtualization



System Exploration  
Kit (Reference Integration)



Automated Driving  
HPC



ADAS-Cockpit (AC)  
HPC



Mechanical  
Housing and  
Cooling Solutions  
(Cooling, Rack & Stack concepts)



Central HPC



Architecture & Consulting

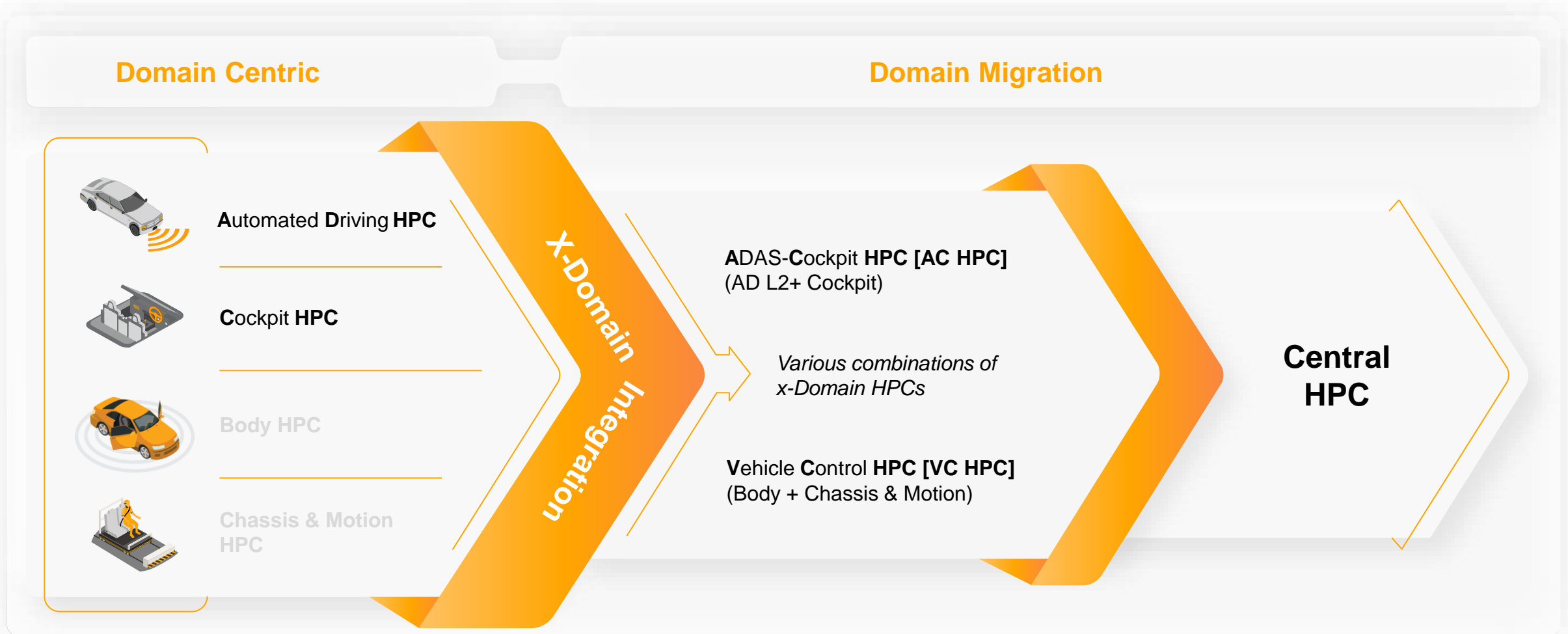
HW & SW Development

Integration & Testing

Production & Maintenance

# From Domain Centric Towards Central HPC

## Overview About Domain Migration



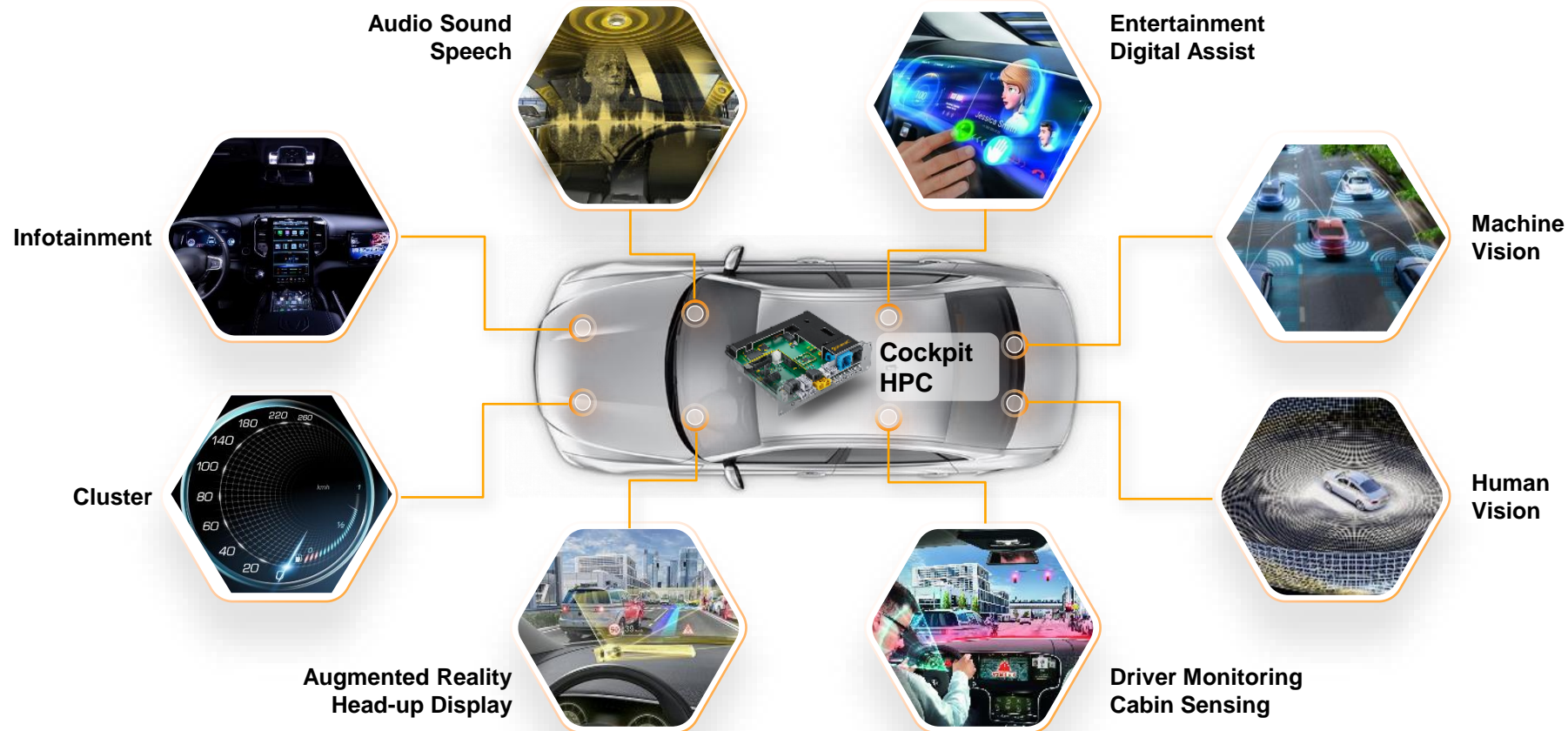
\*HPC: High-Performance Computer

# Cockpit High-Performance Computer

## Scope



“The journey started integrating infotainment and cluster functionalities in one device. Features are continuously added (e.g., cameras, ...)”



### Function List




- > Cluster
- > Infotainment
  - > Radio
  - > Media
  - > Navigation
  - > Phone
  - > Connectivity
- > Audio, Sound, Speech
- > Augmented Reality
  - > Head-up Display
  - > Display
- > Entertainment
  - > Co-Driver Entertainment
  - > Rear-Seat Entertainment
  - > E-Travel Companion
- > Diver and Cabin Sensing
- > Human Vision
  - > 360 deg View
  - > Digital Mirror
- > Machine Vision

# Smart Cockpit HPC Demo Car In Collaboration With Google Cloud



Consumer  
Technology  
Association



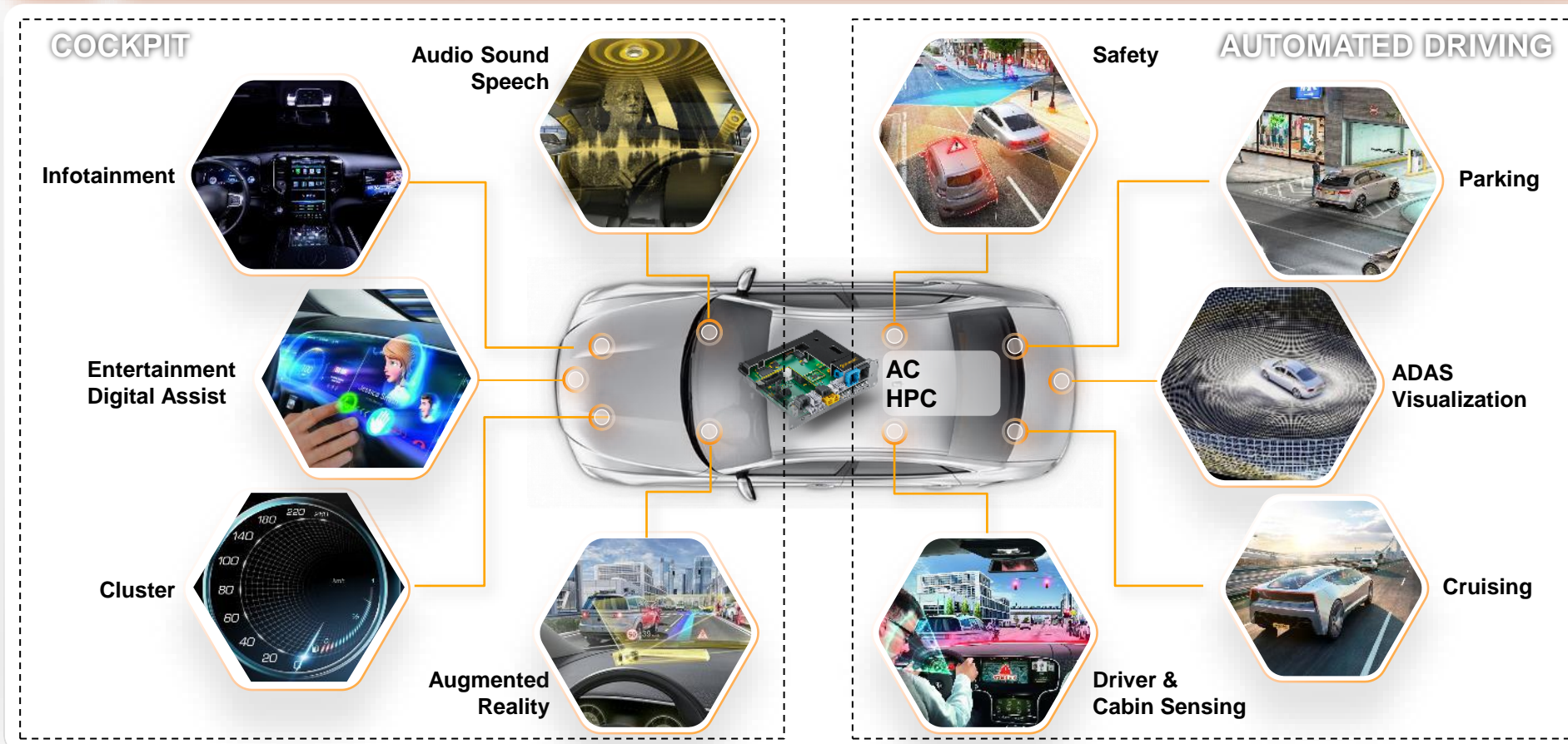
-  Powerful processor of the Telechips Dolphin family
-  Pre-integrated functions for cluster, infotainment and visualization of Advanced Driver Assistance Systems
-  Cost-optimized and with a short development time

# Cross-Domain High-Performance Computer

## Combining ADAS and Cockpit Functionality (AC HPC)



“The journey started integrating cabin sensing into the cockpit HPC. Other functions of automated driving are continuously added.”



### Function List

#### Cockpit

- > Cluster
- > Entertainment & Digital Assist
  - > Co-Driver Entertainment
  - > Rear-Seat Entertainment
- > Infotainment
  - > Radio, Media
  - > Navigation, Connectivity
- > Audio, Sound, Speech
- > Augmented Reality

#### Automated Driving

- > Driver and Cabin Sensing
- > Cruising
  - > Traffic Jam Chauffeur
- > ADAS Visualization
- > Parking
  - > Valet Parking
- > Safety
  - > Lane Departure Warning

# Cross-Domain HPC Technology Car

## Combination of Cockpit and ADAS



Consumer  
Technology  
Association



First driving vehicle with a cross-domain AC HPC



Combining cockpit and advanced driver assistance features on one chip



Milestone on the path towards full domain integration

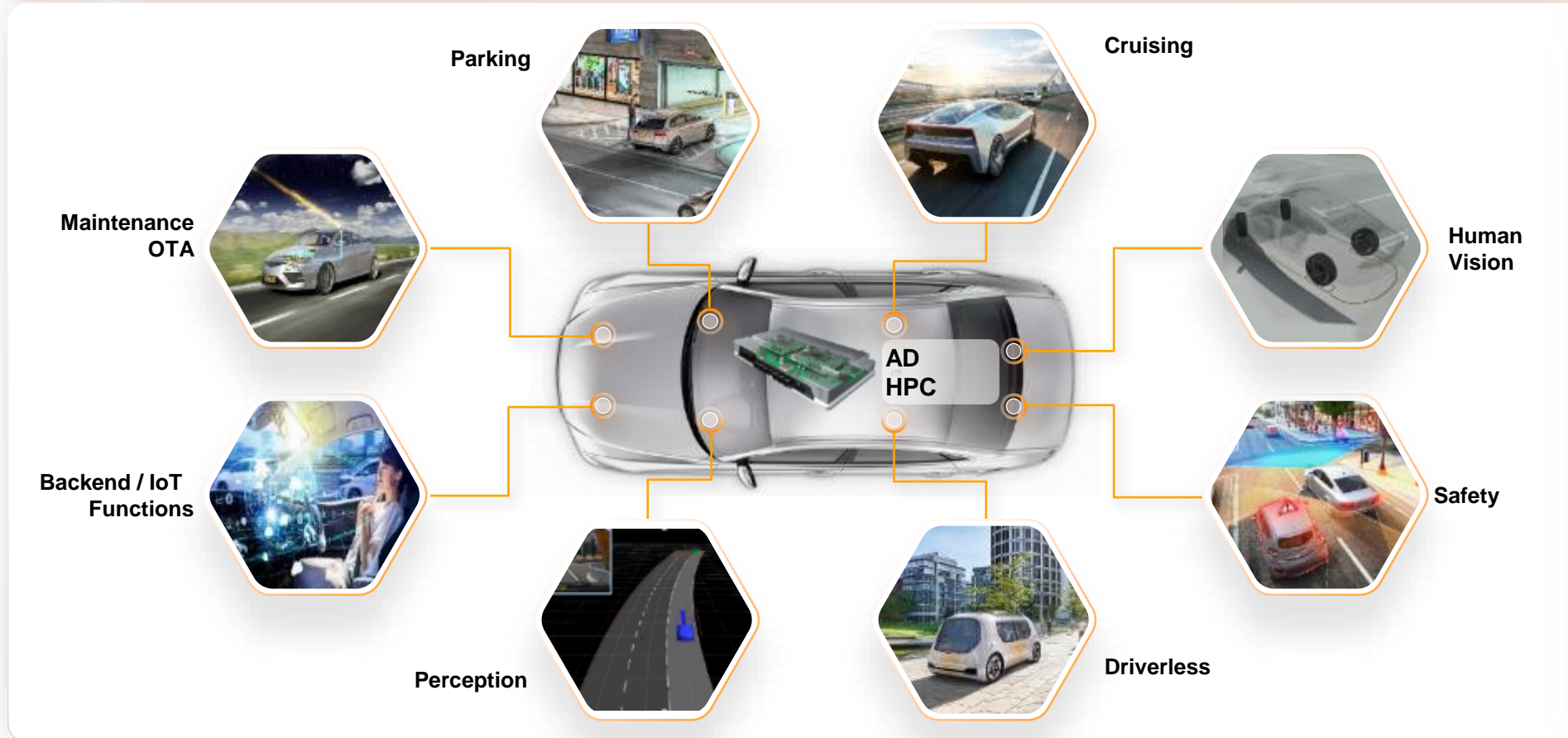


# Automated Driving HPC

## Integration of Assisted and Automated Driving Functions Into One Device



“ADAS functions such as visualization, parking, driving from L2+, and combinations of these functions can be hosted on one device”



### Function List

- › **Parking, e.g.**
  - › Automated Parking
  - › Valet Parking
- › **Cruising, e.g.**
  - › Driver Monitoring
  - › Traffic Jam Chauffeur
- › **Human Vision, e.g.**
  - › Surround View
  - › Transparent Hood
- › **Safety, e.g.**
  - › Lane Departure Warning
  - › Blind Spot Monitoring
- › **Perception**
- › **Backend Functions e.g.**
  - › Big Data
- › **Maintenance / OTA**

# Aurora Truck

## Automated Driving HPC



Consumer  
Technology  
Association



AD HPC hardware for fully driverless (L4) operation of long-haul trucks



ADCU for full-stack fallback-path



Partnership with Ambarella - Software Stack for assisted and automated driving



# Vehicle Control (VC) HPC

## Host for Vehicle Control Core- and Cross-Domain Functions



“We integrate vehicle infrastructure and cross-domain functionalities into one device...”

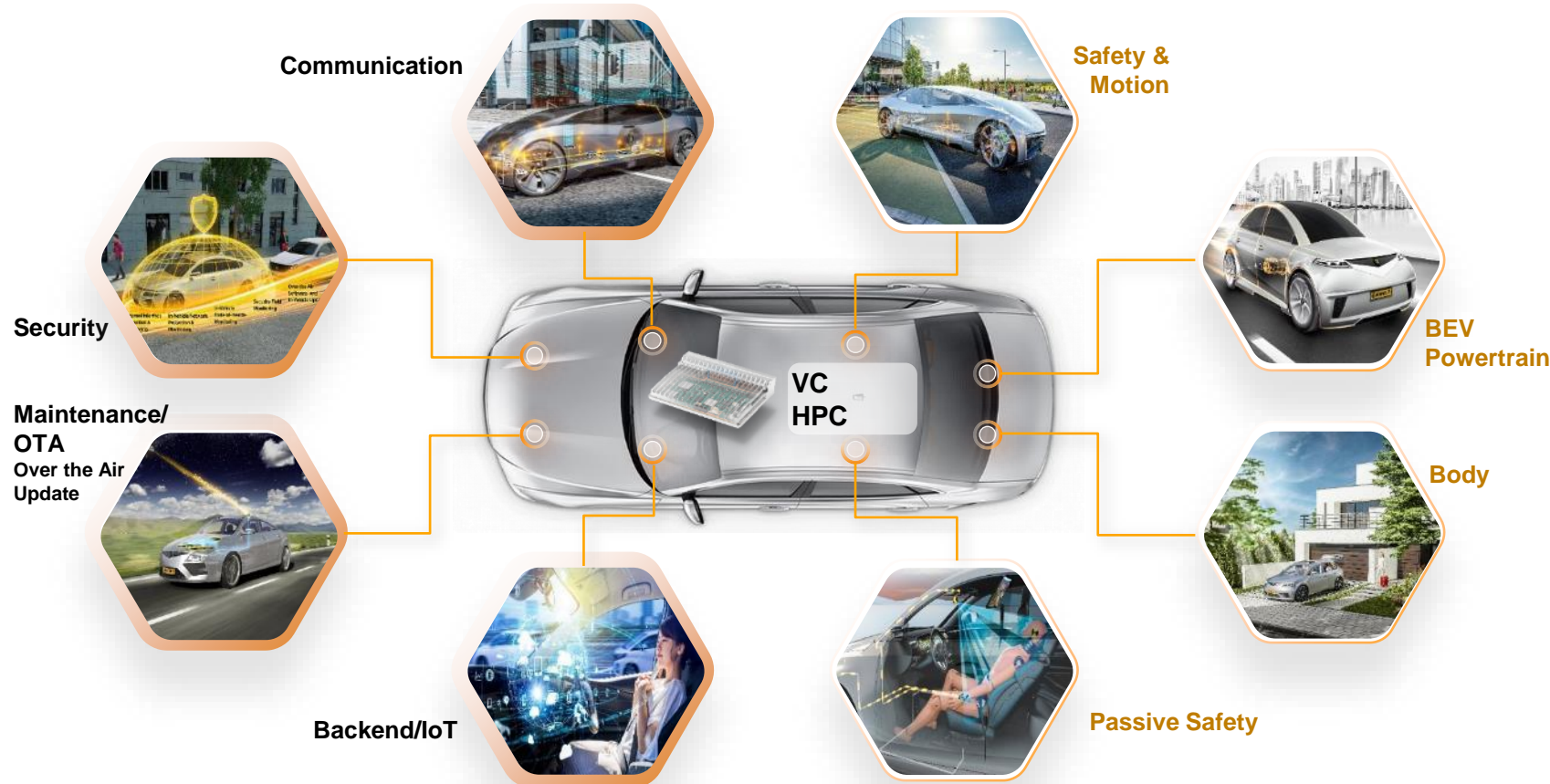
VC Core Functions

Hosted Functions



### Function List

- > **Communication**
  - > Routing, Gateway, ...
- > **Security**
  - > Gateway, Key Management, ...
- > **Maintenance / OTA**
  - > OBD Diagnostic, SW Update, ...
- > **Backend/IoT**
  - > Predictive Maintenance
  - > Big Data (collection), ...
- > **Safety & Motion**
  - > Holistic Motion Control (HMC), ...
- > **BEV Powertrain**
  - > Powertrain: Electric
  - > Charging Management, ...
- > **Body**
  - > Exterior/Interior Light
  - > Air Conditioning, Seat Control, ...
- > **Passive Safety**
  - > Tire Pressure Monitoring
  - > Driver Health Monitoring, ...



BEV = Battery Electrical Vehicle, OBD = On Board Diagnose

# Various VC HPC Platform and Series Products

## Vehicle Control High-Performance Computers



Source: <https://insideevs.de>

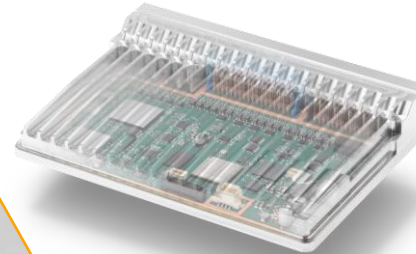


\*ZCU = Zone Control Unit; ICAS1 = InCar Application Server

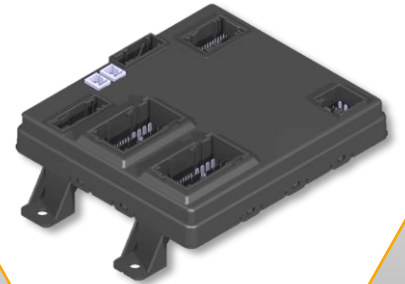
**GAC**



**VC HPC  
Base Platform**



**Hybrid HPC  
(HPC/ZCU)**



**Volkswagen ICAS1  
for ID.Series**



Integration host for vehicle control functions



Central data and communication hub



Master for over-the-air software  
update and upgrades



Vehicle cyber security master

# Zone Control Units – The Next “Layer” Below the HPC

## Essential Components to Realize the SDV

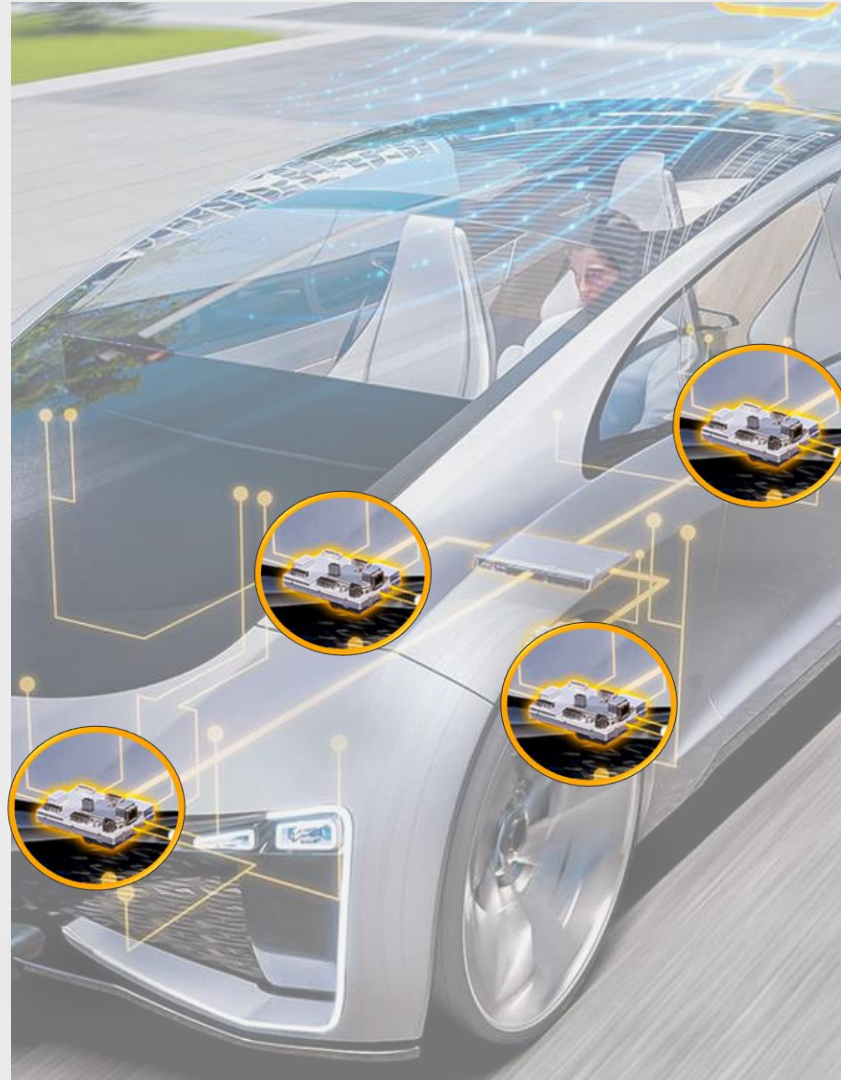
**Manage complexity +**  
Reduce total vehicle system cost

**Consolidate I/Os** and reduce  
ECUs

**Optimize** power & signal  
management

Low effort **Variant Management /**  
**fast time to market**

**SOA Introduction** - “Place” for  
Real Time Functions and StS\*  
conversation



**ZCU allows x-domain zonal  
management of signals, data & power!**

### Input/Output Control

- › **Standardized** data/service interfaces
- › **Signal-to-service** conversion between sensors/actuators & HPC
- › Hosting **time critical real-time** functions

### Communication Gateway

- › **Ethernet** backbone connection to **HPC**
- › CAN, CAN-FD, LIN, 10MBit Ethernet for **zonal network**
- › **Translation** between service-oriented and signal-oriented ECUs

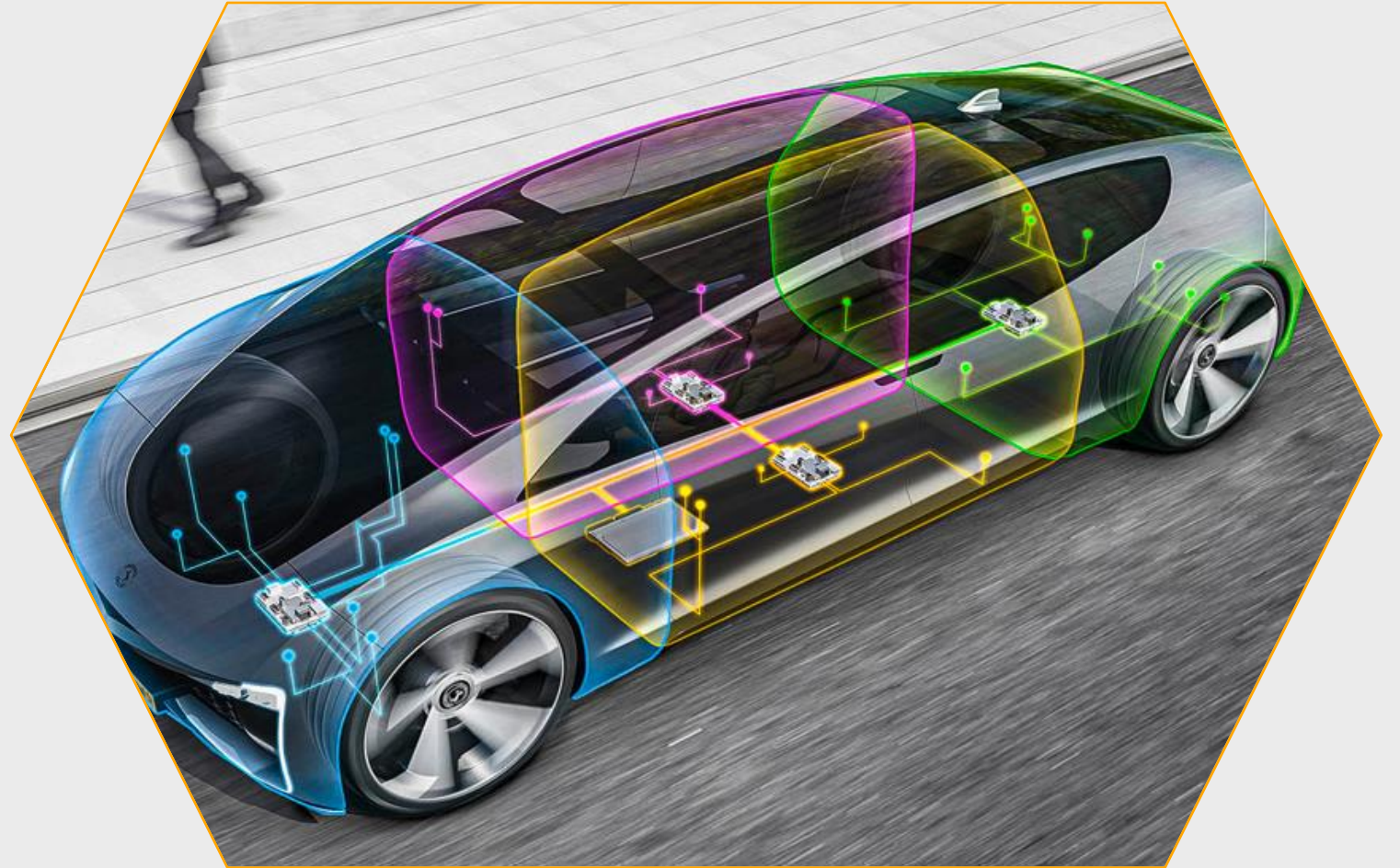
### Smart Power Distribution

- › Intelligent **power distribution** and diagnosis
- › **Smart fusing**/switching up to 40A
- › **Redundancy** (support ASIL-rated power distribution)

# Zone Control Units - Consolidation in Physical Zones

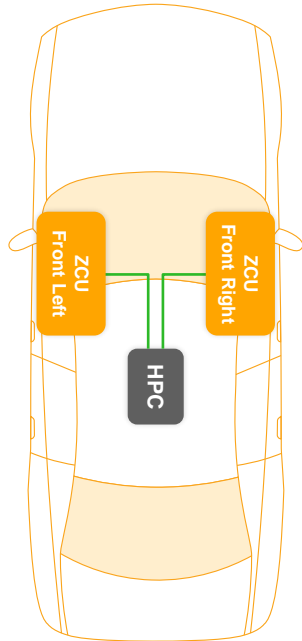
## Real X-Domain Hub Enabling Service-Oriented Architectures

- › Main ECU of a **physical vehicle zone**
- › Located in the vicinity of the sensors/actuators and peripheral devices
- › **Hub for x-domain zonal management** of signals, data and power

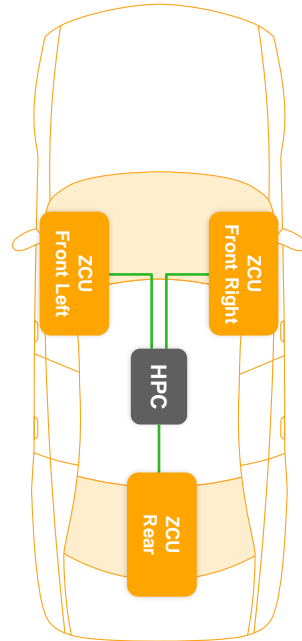


# Server-Zone Architecture

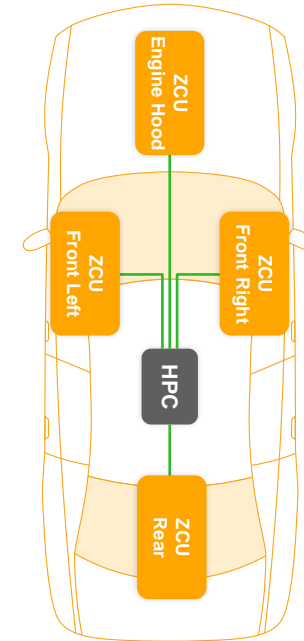
## Scalability Enables X-Carline Vehicle



e.g. A – vehicle segment



e.g. B/C – vehicle segment



e.g. D – vehicle segment

### Remarks

Beyond the above shown star topology an optional CAN ring topology can be applied, too. Any other vehicle architecture with e.g., up to 8 ZCUs can be supported due to modularity and scalability.

ZCU = Zone Control Unit.

# Zone Control Unit Platform

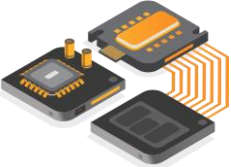
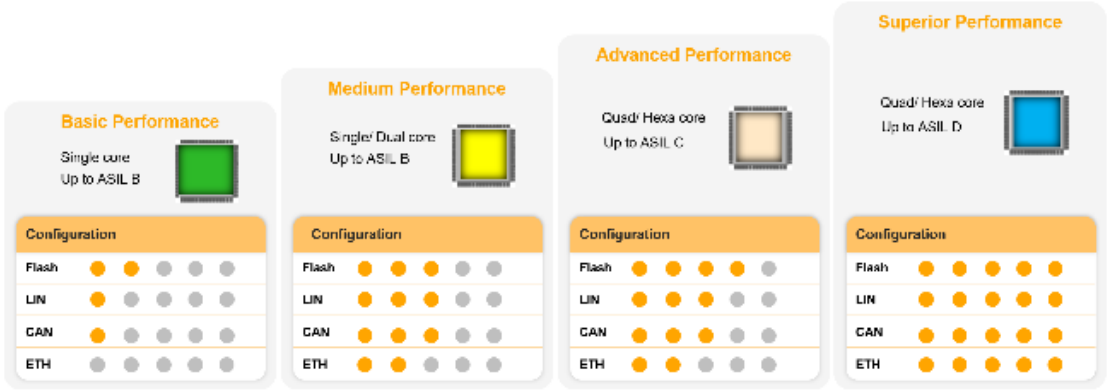
## Scalability and Modularity

Continental's Zone Control Unit Platform supports the market needed variety with a well-defined scalability and modularity concept



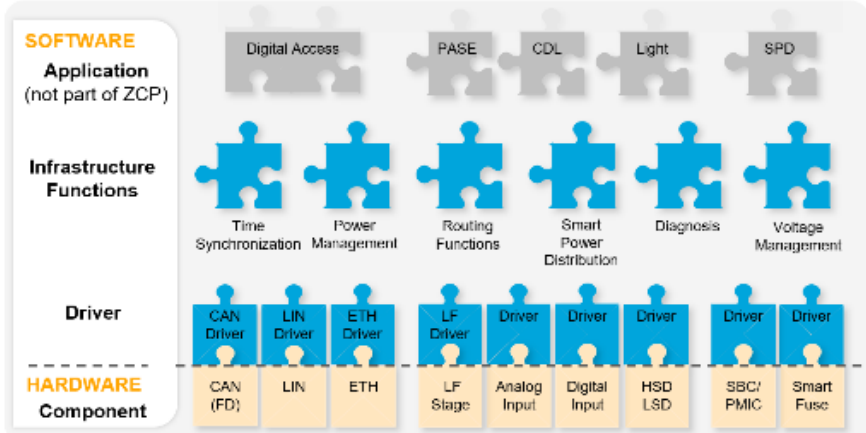
### Scalability

Ability to support lower and higher-level requirements (µC performance, amount of IOs, interfaces,...)



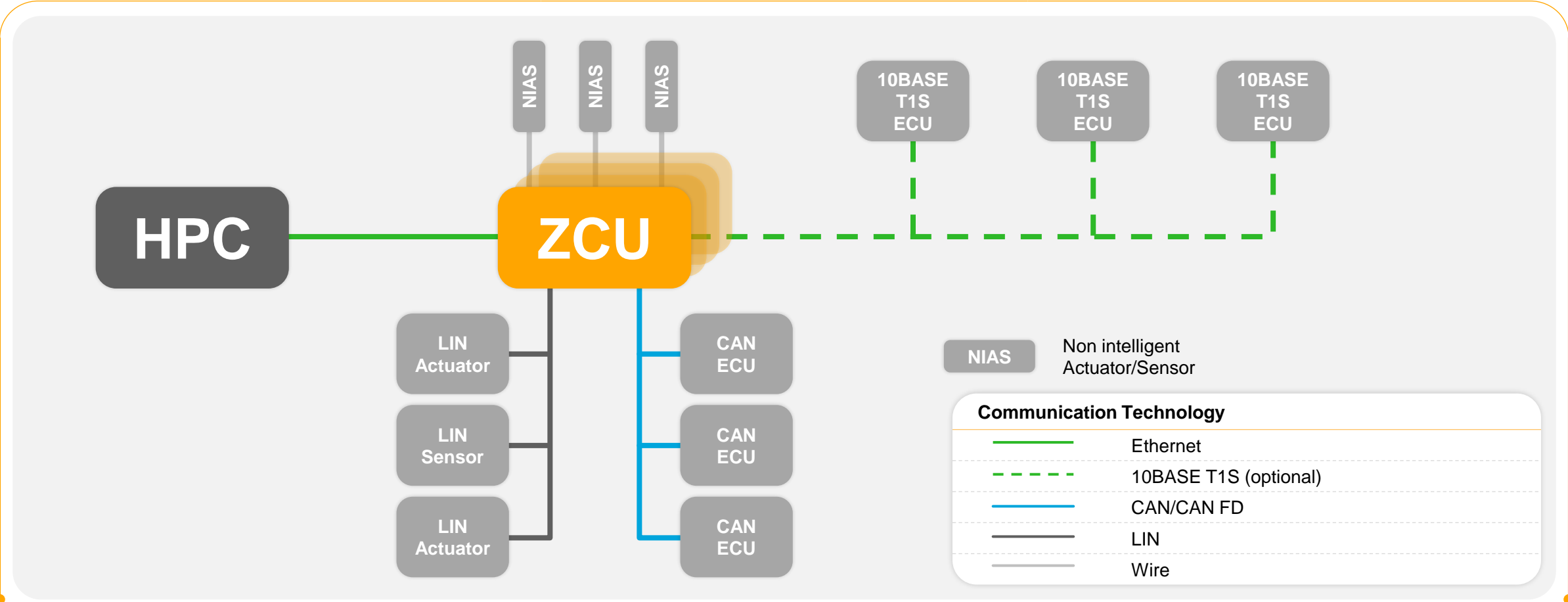
### Modularity

Exchangeability of solutions to cover the specific needs of the OEMs



# Server-Zone Architecture

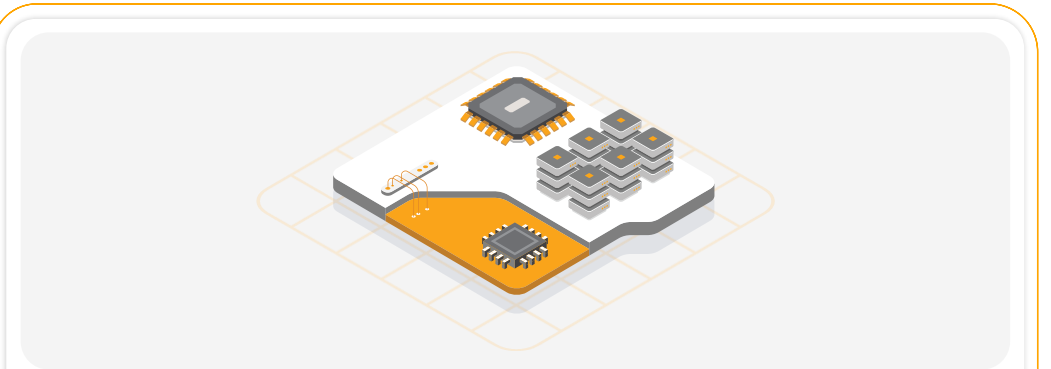
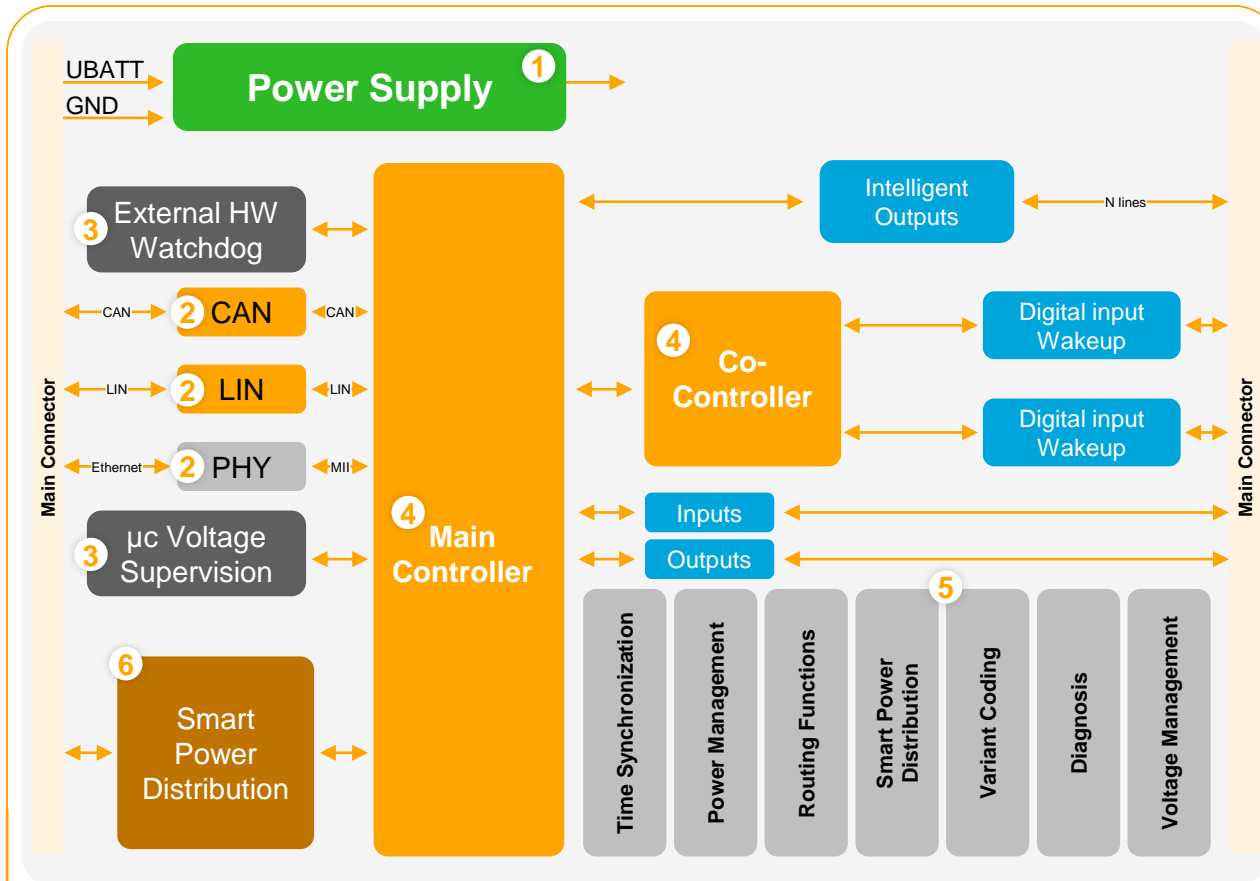
## Main Interconnection Scheme for Zone Control Unit



ZCU = Zone Control Unit; HPC = High Performance Computer; LIN = Local Interconnect Network; CAN = Controller Area Network; CAN FD = Controller Area Network Flexible Data Rate; 10BASE T1S = 10 MBps Multidrop Ethernet via twisted pair copper wire; NIAS = Non-Intelligent Actuator Sensor

# Zone Control Unit Platform

## Backbone - Content



### Backbone Elements

- 1 | Power supply (scalable in relation to ASIL level)
- 2 | Communication interfaces (modular and scalable)
- 3 | Microcontroller supervision (scalable in relation to ASIL level)
- 4 | Microcontroller topology (Co-controller is optional)
- 5 | Infrastructure functions (modular, partly optional)
- 6 | Smart Power Distribution (SPD)

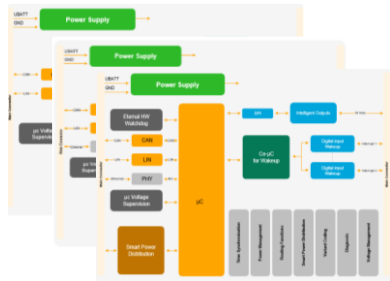
Security and safety measures are pre-integrated in all backbone variants!

µC = Microcontroller, PHY = physical layer, SPI = Serial peripheral interface

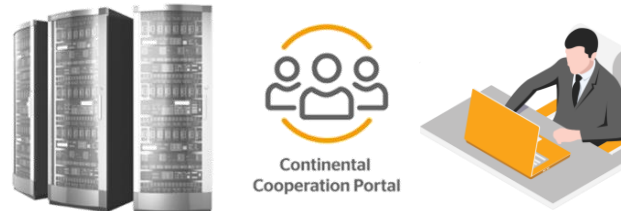
# Zone Control Unit Platform

## Flexible Integration Process

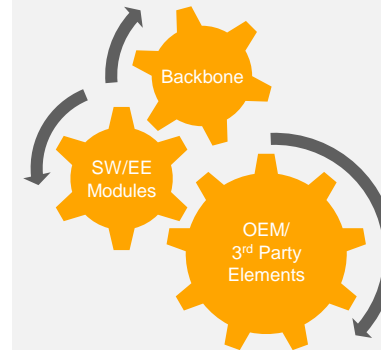
### Platform Backbone Selection



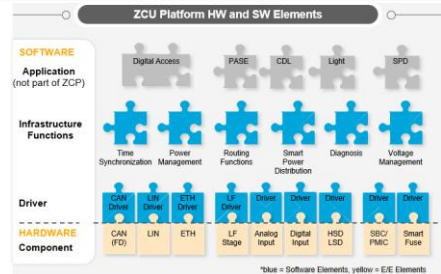
### Customer/ 3rd Party Supplier interface



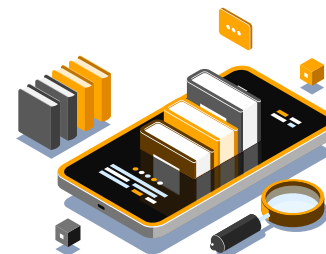
### Integration Process



### Platform Modules Selection



### Continental Function Library



Advanced integration process ensures efficient application development!

# Agenda

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1	From SW-Defined Vehicle to User-Defined Vehicle	Gilles Mabire	3
2	CAEdge: SDV Development with a Cloud-Based Framework	Andreas Greff	10
3	Virtualization	Andreas Greff, Karsten Michels	18
4	Server-Zone Portfolio	Karsten Michels, Gerhard Guentner	27
<b>5</b>	<b>Function as a Product</b>	<b>Gerhard Guentner</b>	<b>46</b>
6	Summary	Gilles Mabire	52

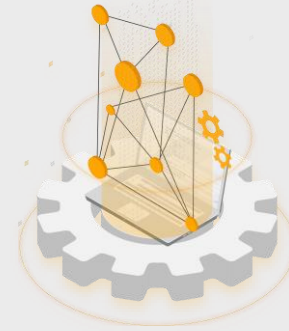
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# Industry Challenges

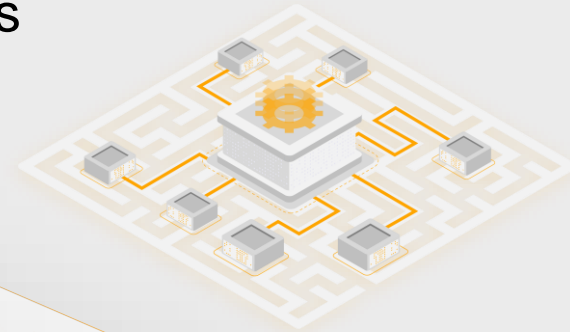
1

Software complexity increases



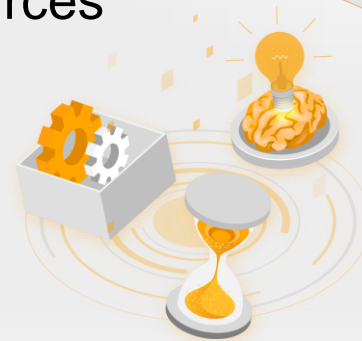
2

Multiplication of software suppliers



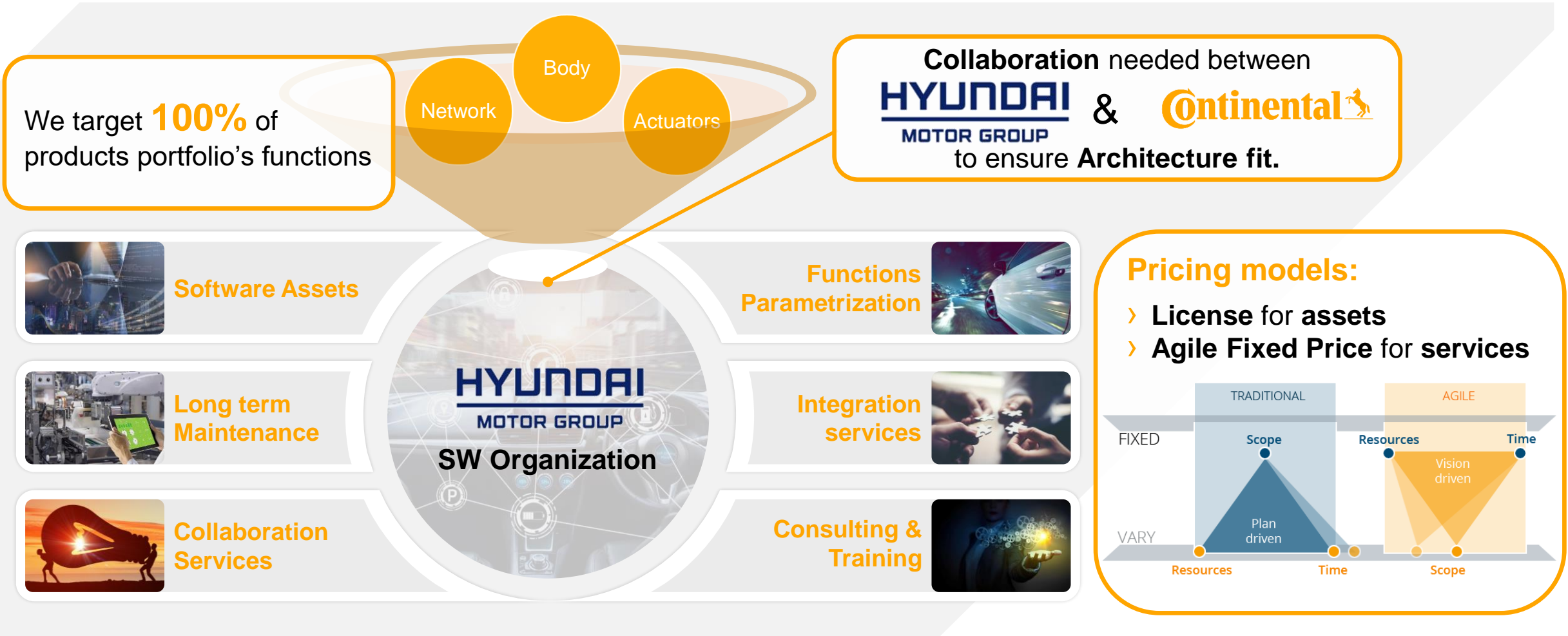
3

Limited resources



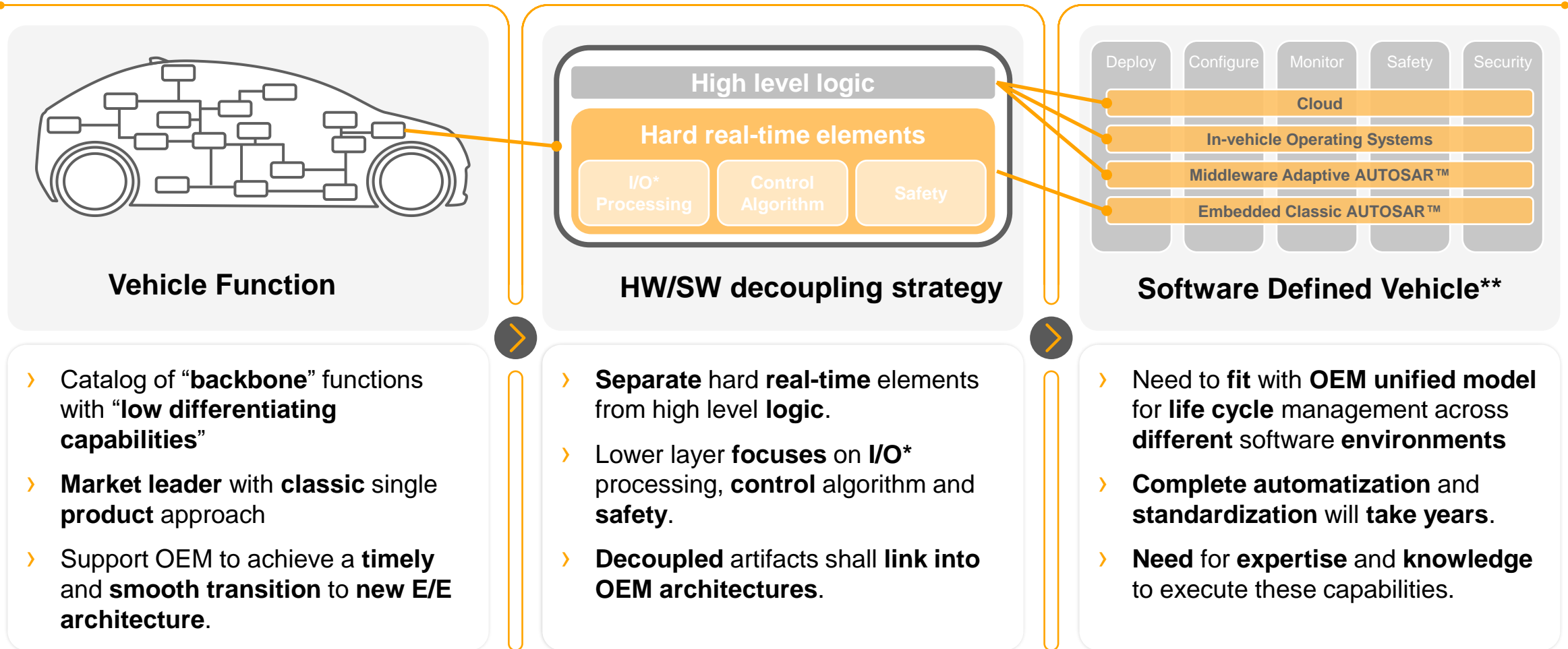
# Our Value Proposition: Function as a Product

## Function Application Layer Solutions



# What does it mean for our function's portfolio?

## OEM involvement needed right from the beginning



\* I/O = input/output, \*\* Non-exhaustive capability model

# Function as a Product

## Key Take Away



Function as a Product means software assets and the services around to ensure seamless integration and maintenance.



Function as a Product serves every stage of the OEM Software-Defined vehicles transformation.



Function as a Product targets at first the backbone functions of the vehicle.



# Agenda

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# Road to Cloud Ecosystem

Enable. Develop. Integrate.

With our expertise across the entire ecosystem, we are able to connect all the dots and provide dedicated solutions to support our customers, realize their vision.

